24 / 5 / 17

Linear and Parabolic Motion - Lesson 1

Displacement, Velocity and Acceleration

LI

- Know the links between displacement, velocity and acceleration.
- Perform rectilinear motion calculations involving these
 3 physical quantities.

<u>SC</u>

- Differentiate and integrate powers and trig. functions.
- Substitution.

Basic Definitions Regarding Objects

Definition:

A **body** is a physical object.

Definition:

A (point) particle (aka pointlike particle or ideal particle) is an idealization of a body, represented mathematically as zero-dimensional (no spatial extent) but still retaining physical properties such as mass.

Definition:

A physical property of a body is **uniform** if that property does not change over time.

Definition:

A reference frame is a system of coordinates used to describe the motion of a body.

Rectilinear means in a straight line

Definition:

The displacement (from the origin) of a particle is a vector function of time, where \mathbf{u} is a unit vector (normally taken to be \mathbf{i} , \mathbf{j} or \mathbf{k}) in the direction of motion,

$$s(t) = s(t) u = x(t) u = x(t)$$

The distance a particle travels is the magnitude of displacement,

$$s(t) = |s| = x(t)$$

Displacement is a vector, whereas distance is a scalar. They both have SI unit the metre (m).

Sometimes 'r' instead of 's' is used for displacement

Definition:

The velocity of a particle is the time-derivative of its displacement,

$$v(t) = \frac{ds}{dt} \equiv \dot{s}(t) \stackrel{def}{=} \dot{s}(t) \mathbf{u}$$

The **speed** of a particle is the magnitude of its velocity,

$$v(t) \stackrel{\text{def}}{=} |v| = \dot{s}(t) = \dot{x}(t)$$

Velocity is a vector, whereas speed is a scalar. They both have SI unit the metre per second (m s $^{-1}$).

Corollary:

Displacement is the integral of velocity,

$$s(t) = \int v(t) dt \stackrel{\text{def}}{=} \int v(t) dt \mathbf{u}$$

Corollary:

An object with zero velocity has constant displacement.

Definition:

The **acceleration vector** of a particle is the first derivative of velocity (equivalently, the second derivative of displacement),

$$a(t) \stackrel{def}{=} \frac{d\mathbf{v}}{dt} \equiv \dot{\mathbf{v}}(t) = \ddot{\mathbf{s}}(t) \equiv \frac{d^2\mathbf{s}}{dt^2}$$

The magnitude of acceleration of a particle is the magnitude of its acceleration vector,

$$a(t) \stackrel{def}{=} |a| = \dot{v}(t) = \ddot{s}(t) = \ddot{x}(t)$$

Acceleration has SI unit the metre per second squared (m s^{-2}).

Corollary:

Velocity is the integral of acceleration,

$$v(t) = \int a(t) dt \stackrel{def}{=} \int a(t) dt \mathbf{u}$$

Corollary:

An object with zero acceleration has constant velocity.

Useful Terminology

Constant - unchanging

At rest - velocity = 0

Initially - time starts at 0

At origin - displacement = 0

Connections Between Displacement, Velocity and Acceleration

$$\frac{\frac{d}{dt}}{\int} \underline{\underline{v}(t)} \frac{\frac{d}{dt}}{\int} \underline{\underline{a}(t)}$$

Example 1

A particle has velocity $\underline{\mathbf{v}}$ (t) = $(3 t^2 - 4 t) \underline{\mathbf{i}}$. Initially, the particle is at a distance of -3 m from the origin of the coordinate system.

Calculate the particle's:

- (a) displacement at time 4 s.
- (b) distance from the origin at t = 1 s.
- (c) acceleration vector at t = 2/3 s.

(a)
$$\underline{\mathbf{r}}(t) = \int \underline{\mathbf{v}}(t) dt$$

$$\therefore \quad \underline{\mathbf{r}}(t) = \int (3t^2 - 4t) \underline{\mathbf{i}} dt$$

$$\Rightarrow \quad \underline{\mathbf{r}}(t) = (t^3 - 2t^2) \underline{\mathbf{i}} + \underline{\mathbf{C}}$$

$$\underline{\mathbf{r}}(0) = -3 \underline{\mathbf{i}} \text{ gives,}$$

$$-3 \underline{\mathbf{i}} = (0^3 - 2.0^2) \underline{\mathbf{i}} + \underline{\mathbf{C}}$$

$$\Rightarrow \quad \underline{\mathbf{C}} = -3 \underline{\mathbf{i}}$$

$$\therefore \quad \underline{\mathbf{r}}(t) = (t^3 - 2t^2 - 3) \underline{\mathbf{i}}$$

$$\therefore \quad \underline{\mathbf{r}}(4) = ((4)^3 - 2(4)^2 - 3) \underline{\mathbf{i}}$$

$$\Rightarrow \quad \underline{\mathbf{r}}(4) = 29 \underline{\mathbf{i}} \text{ m}$$

(b)
$$\underline{r}(1) = ((1)^3 - 2(1)^2 - 3)\underline{i}$$
 $\Rightarrow \underline{r}(1) = -4\underline{i}$
 $\therefore \qquad r(1) = 4 \text{ m}$

(c)
$$\underline{\mathbf{a}}(t) = \frac{d}{dt} \underline{\mathbf{v}}(t)$$

$$\Rightarrow \underline{\mathbf{a}}(t) = \frac{d}{dt} (3 t^2 - 4 t) \underline{\mathbf{i}}$$

$$\Rightarrow \underline{\mathbf{a}}(t) = (6 t - 4) \underline{\mathbf{i}}$$

$$\therefore \underline{\mathbf{a}}(2/3) = (6 (2/3) - 4) \underline{\mathbf{i}}$$

$$\Rightarrow \underline{\mathbf{a}}(2/3) = \underline{\mathbf{0}} \, \mathrm{m} \, \mathrm{s}^{-2}$$

Example 2

A particle has acceleration \underline{a} (t) = (sin 2 t) \underline{k} . Initially, the particle is at rest at the origin of the coordinate system.

Calculate the:

- (a) particle's speed at time $\pi/2$ s.
- (b) particle's distance from the origin at $t = \pi/2$ s.
- (c) times at which the acceleration is zero.

(a)
$$\underline{\mathbf{v}}(t) = \int \underline{\mathbf{a}}(t) dt$$

$$\therefore \quad \underline{\mathbf{v}}(t) = \int (\sin 2t) \, \underline{\mathbf{k}} \, dt$$

$$\Rightarrow \quad \underline{\mathbf{v}}(\dagger) = (-1/2\cos 2\,\dagger)\,\underline{\mathbf{k}} + \underline{\mathbf{C}}$$

$$\underline{\mathbf{v}}(0) = \underline{\mathbf{0}}$$
 gives,

$$\underline{\mathbf{0}} = (-1/2.1)\,\mathbf{\underline{k}} + \underline{\mathbf{C}}$$

$$\Rightarrow \quad \underline{\mathbf{C}} = 1/2 \, \underline{\mathbf{k}}$$

$$\underline{v}$$
 (†) = (1/2 - 1/2 cos 2 †) \underline{k}

$$\therefore \quad \underline{\mathbf{v}}(\pi/2) = (1/2 - 1/2 \cos \pi) \underline{\mathbf{k}}$$

$$\Rightarrow$$
 $\underline{\mathbf{v}}(\pi/2) = \underline{\mathbf{k}} \ \mathrm{m} \ \mathrm{s}^{-1}$

$$\therefore \qquad v(\pi/2) = 1 \text{ m s}^{-1}$$

(b)
$$\underline{\mathbf{r}}(t) = \int \underline{\mathbf{v}}(t) dt$$

$$\therefore \qquad \underline{\mathbf{r}}(t) = \int (1/2 - 1/2 \cos 2 t) \, \underline{\mathbf{k}} \, dt$$

$$\Rightarrow \qquad \underline{\mathbf{r}}(t) = (t/2 - 1/4 \sin 2 t) \underline{\mathbf{k}} + \underline{\mathbf{D}}$$

$$\underline{\mathbf{r}}(0) = \underline{\mathbf{0}}$$
 gives,

$$0 = (0/2 - 1/4.0) k + D$$

$$r(t) = (t/2 - 1/4 \sin 2 t) k$$

$$\therefore \quad \underline{\mathbf{r}}(\pi/2) = (\pi/4 - 1/4 \sin \pi) \, \underline{\mathbf{k}}$$

$$\Rightarrow \quad \underline{\mathbf{r}}(\pi/2) = \pi/4 \ \underline{\mathbf{k}}$$

$$\therefore \qquad r(\pi/2) = \pi/4 \text{ m}$$

(c)
$$\underline{a}(t) = \underline{0}$$

$$\therefore \quad (\sin 2 t) \, \underline{\mathbf{k}} = \underline{\mathbf{0}}$$

$$\therefore$$
 $\sin 2 t = 0$

$$\Rightarrow$$
 $t = (n\pi/2) s$ $(n = 0, 1, 2, 3, ...)$

Blue Book

• pg. 397 - 400 Ex. 16 A Q 10 - 14, 44 - 48.