

Section B (Numerical Analysis 1 and 2)

Marks

ONLY candidates doing the course Numerical Analysis 1 and 2 and one unit chosen from Mathematics 1 (Section D), Statistics 1 (Section E) and Mechanics 1 (Section G) should attempt this Section.

Answer all the questions.

Answer these questions in a separate answer book, showing clearly the section chosen.

- B1.** The function f is defined for $x > 0.8$ by $f(x) = \frac{1}{5x-4}$.
- The polynomial p is the Taylor polynomial of degree two for the function f near $x = 1$. Express $p(1+h)$ in the form $c_0 + c_1h + c_2h^2$. 3
- Use this polynomial to estimate the value of $f(0.99)$. 2
- State, with a reason, whether or not $f(x)$ is sensitive to small changes in x in the neighbourhood of $x = 1$. 1
- B2.** The following data are available for a function f :
- | | | | |
|--------|--------|--------|--------|
| x | 0 | 2 | 5 |
| $f(x)$ | 1.3271 | 1.5238 | 1.8516 |
- Use the quadratic Lagrange interpolation formula to estimate $f(3)$. 3
- B3.** In the usual notation for forward differences of function values $f(x)$ tabulated at equally spaced values of x ,
- $$\Delta f_i = f_{i+1} - f_i,$$
- where $f_i = f(x_i)$ and $i = \dots -2, -1, 0, 1, 2, \dots$
- Show that $\Delta^3 f_0 = f_3 - 3f_2 + 3f_1 - f_0$. 2
- If each value of f_i is subject to an error whose magnitude is less than or equal to ϵ , determine the magnitude of the maximum possible rounding error in $\Delta^3 f_0$. 1
- Rounded values of a function f are known to be $f_0 = 1.311$, $f_1 = 1.416$, $f_2 = 1.532$, $f_3 = 1.658$. Obtain $\Delta^3 f_0$ and the magnitude of the maximum rounding error in $\Delta^3 f_0$. 2
- Hence state whether or not this third difference appears to be significantly different from zero. 1
- B4.** The following data (accurate to the degree implied) are available for a function f :
- | | | | | | | |
|--------|-------|-------|-------|-------|-------|-------|
| x | 1.0 | 1.1 | 1.2 | 1.3 | 1.4 | 1.5 |
| $f(x)$ | 1.263 | 1.456 | 1.696 | 1.991 | 2.351 | 2.782 |
- (a) Construct a difference table of fourth order for the data. 3
- (b) Using the Newton forward difference formula of degree three, and working to three decimal places, obtain an approximation to $f(1.18)$. 3

- B5. The sequence $\{a_r\}$ is defined by the recurrence relation

$$5a_{n+1} + 3a_n = 1, \quad \text{with } a_0 = 2.$$

Trace the sequence as far as the term a_4 . (Work to two decimal places where appropriate.)

2

Display the convergence of the sequence using a cobweb diagram, ie a sketch based on drawing the line segments between the points with coordinates (a_0, a_0) , (a_0, a_1) , (a_1, a_1) , (a_1, a_2) , (a_2, a_2) , etc.

3

Determine the x -coordinate of the point at the centre of the cobweb diagram, ie the fixed point of the sequence.

1

- B6. Express the polynomial $f(x) = 3.1x^4 + 2.8x^3 - 4.2x + 2.0$ in nested form and evaluate $f(1.2)$ to two decimal places.

2

Given that the coefficients of $f(x)$ are rounded to the accuracy implied, determine the maximum possible value of $f(1.2)$.

1

- B7. Write the following equations in diagonally dominant form:

$$0.71x_1 + 2.78x_2 - 0.08x_3 = 3.18$$

$$0.46x_1 - 0.34x_2 + 5.17x_3 = 9.25$$

$$4.24x_1 + 0.27x_2 - 0.46x_3 = -1.14.$$

1

Explain why this is necessary when the equations are to be solved using an iterative procedure.

1

Use the Jacobi iterative procedure, with $x_1 = x_2 = x_3 = 0$ as a first approximation, to obtain the *first iterates* of x_1 and x_2 for the solution of these equations.

1

- B8. (a) Using a Taylor polynomial of degree two, or otherwise, derive the trapezium rule over a single strip and the corresponding principal error term.

5

- (b) Use the composite trapezium rule with four strips to obtain an estimate for the integral

$$\int_1^{1.4} x^2 \ln x \, dx.$$

Perform the calculations using four decimal places.

2

- (c) Given that for $f(x) = x^2 \ln x$, $f''(x) = 2 \ln x + 3$, obtain the maximum value of $x^2 \ln x$ on the interval $[1, 1.4]$ and hence obtain an estimate of the maximum truncation error in the integral.

3

Hence state the value of the integral to a suitable accuracy.

1

[Turn over

- B9.** The system of linear equations

$$\begin{pmatrix} -2.8 & 1.5 & 0.7 \\ 3.7 & -4.2 & 2.2 \\ 0.0 & 2.6 & 7.1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3.1 \\ 8.4 \\ -2.8 \end{pmatrix}$$

has arisen in the solution of a problem.

Use Gaussian elimination with partial pivoting to solve the system, incorporating a row check and carrying two guard figures in the calculation. Record your answers rounded to one decimal place.

6

- B10.** The equation $f(x) = 0$ has a root close to $x = x_0$. By drawing a suitable graph to illustrate this situation, derive the formula for the first iteration of the Newton-Raphson method of solution of $f(x) = 0$. Hence explain how the general formula is obtained.

3

It is known that the equation $f(x) = 0$, where $f(x) = e^x - 3x^2 - 1$, has three distinct real roots one of which lies in the interval $[3, 4]$.

Given that $\frac{d}{dx}(e^x) = e^x$, use the Newton-Raphson method to determine this root correct to three decimal places.

3

Explain the term *ill-conditioning* in relation to the determination of the roots of the equation $f(x) = 0$. It is known that the other two roots lie in the narrow interval $[0, 0.5]$.

Use a diagram to explain why the Newton-Raphson method may be difficult to use in the determination of these roots.

3

- B11.** A predictor-corrector method for the solution of a differential equation uses Euler's method as predictor. Explain, with the aid of a diagram, how the trapezium rule may be used as the corrector.

3

Use this predictor-corrector method with two applications of the corrector to obtain a solution at $x = 1.1$ of the differential equation

$$\frac{dy}{dx} = (x^2 - y + 1) \cos x, \quad y(1) = 1.$$

Use step size 0.1 and carry four decimal places in the calculation.

6

[END OF SECTION B]

All candidates who have attempted Section B (Numerical Analysis 1 and 2) should now attempt ONE of the following

Section D (Mathematics 1) on Page fourteen

Section E (Statistics 1) on Pages fifteen and sixteen

Section G (Mechanics 1) on Pages nineteen and twenty.